

8. One-Dimensional Flows

8.1 Introduction

- * Navier-Stokes eq'ns and continuity eq'n are four **coupled, nonlinear PDE**. \Rightarrow extremely difficult system
- * In most situations of practical interest, a good deal of **approximation** is required, often followed by **numerical computation**.

The general procedure for the solution of flow problems is

1. Utilize understanding of the process to determine upon which independent variables each of the velocity components depends.
 \Rightarrow **kinematic assumptions**
2. Substitute into the continuity eq'n to ensure that the dependence assumed in step 1 is **consistent with continuity**.
3. Substitute into the momentum or **Navier-Stokes equations** and solve them.

8.2 Plane Poiseuille Flow

Problem description:

Consider the flow of an incompressible Newtonian fluid in the x direction at a steady state through a rectangular channel of very large aspect ratio.

$H/W \ll 1$: negligible side wall effects

$H/L \ll 1$: negligible entrance and exit effects \Rightarrow fully developed

The flow is not turbulent.

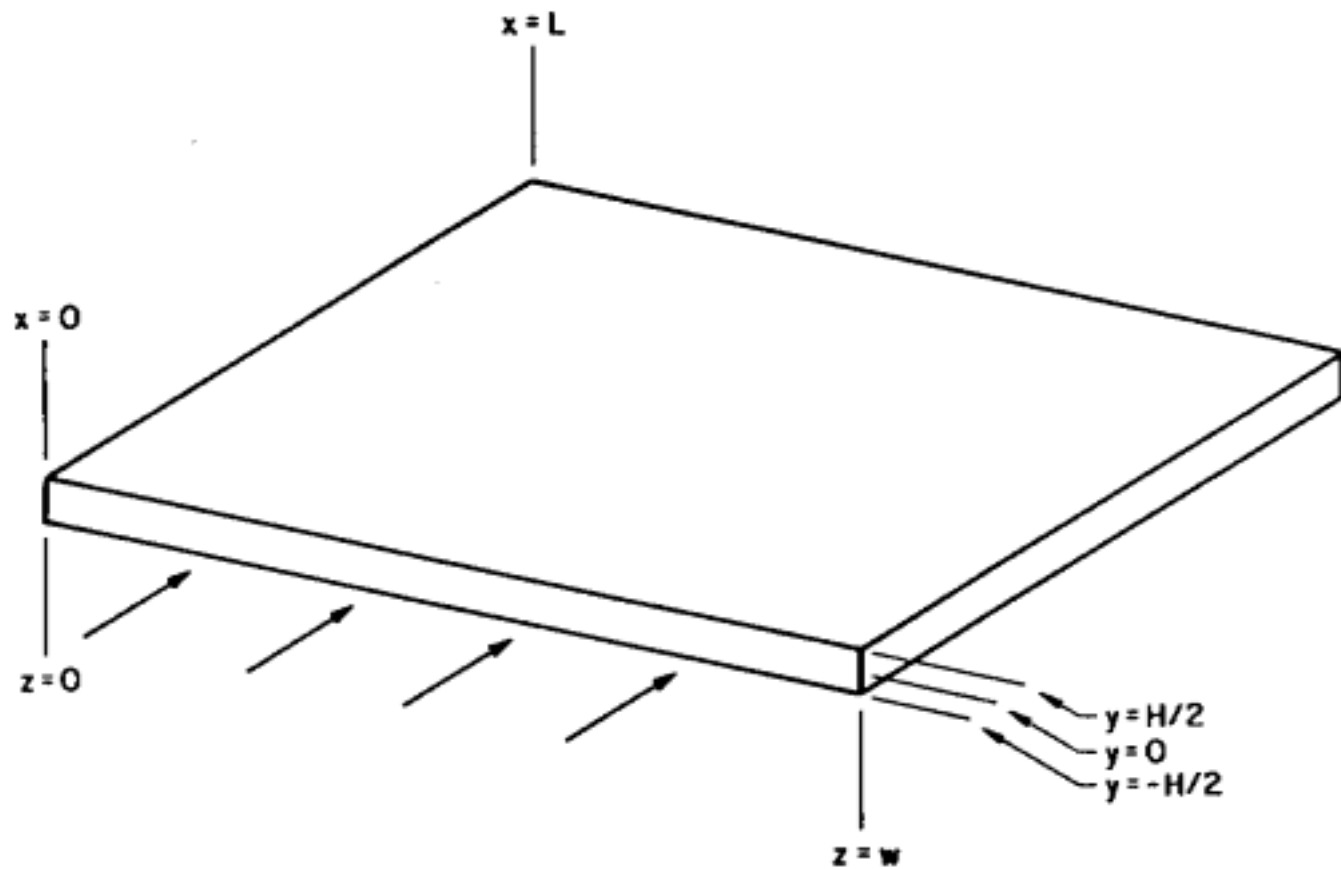


Fig. 8-1. Schematic of flow in a plane channel with large aspect ratio.

Direct solution:

The flow is **fully developed**. \Rightarrow no variations in x direction

$$\frac{\partial v_x}{\partial x} = \frac{\partial v_y}{\partial x} = \frac{\partial v_z}{\partial x} = 0$$

No side wall effects \Rightarrow no variations in z direction

$$\frac{\partial v_x}{\partial z} = \frac{\partial v_y}{\partial z} = \frac{\partial v_z}{\partial z} = 0$$

Therefore, $v_x = v_x(y)$, $v_y = v_y(y)$, $v_z = v_z(y)$

We further anticipate $v_y = v_z = 0$.

The continuity eq'n in Cartesian coordinates is automatically

satisfied.
$$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0$$

Navier-Stokes eq'ns:

$$x \text{ component : } 0 = -\frac{\partial P}{\partial x} + \eta \frac{d^2 v_x}{dy^2}$$

$$y \text{ component : } 0 = -\frac{\partial P}{\partial y}$$

$$z \text{ component : } 0 = -\frac{\partial P}{\partial z}$$

Therefore, $P = P(x)$,

and
$$\eta \frac{d^2 v_x}{dy^2} = \frac{dP}{dx}$$

function of y only = function of x only = constant = $\Delta P/L$

where $\Delta P = P_{x=L} - P_{x=0} < 0$

After the integration, we have

$$v_x = \frac{1}{2\eta} \frac{\Delta P}{L} y^2 + C_1 y + C_2$$

Apply the no-slip boundary conditions to determine C_1 and C_2 .

$$v_x = 0 \quad \text{at} \quad y = \pm H/2$$

$$\Rightarrow C_1 = 0 \quad \text{and} \quad C_2 = -\frac{1}{2\eta} \frac{\Delta P}{L} \frac{H^2}{4}$$

$$\therefore v_x = \frac{H^2}{8\eta} \left(-\frac{\Delta P}{L}\right) \left[1 - \left(\frac{2y}{H}\right)^2\right] \quad : \text{ parabolic profile}$$

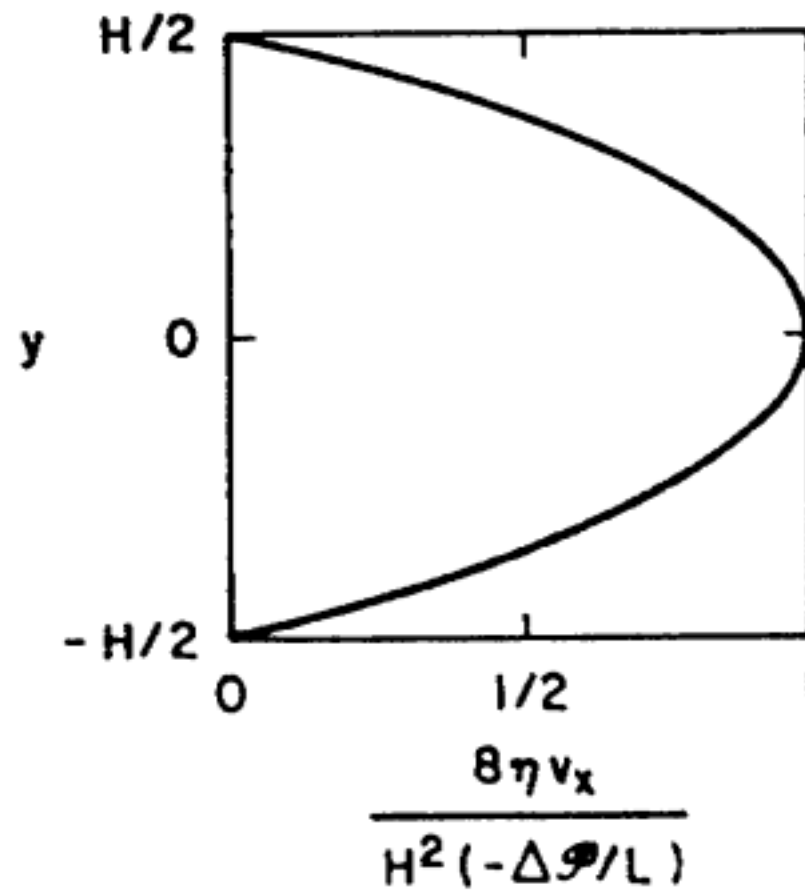


Fig. 8-2. Velocity profile for laminar flow with a pressure gradient between infinite stationary planes.

The flow rate Q is

$$Q = WH \langle v_x \rangle = \int_{area} v_x dA = W \int_{-H/2}^{H/2} v_x dy$$

or the average velocity $\langle v_x \rangle$ is

$$\begin{aligned} \langle v_x \rangle &= \frac{1}{H} \int_{-H/2}^{H/2} v_x dy = \frac{H^2}{8\eta H} \left(-\frac{\Delta P}{L}\right) \int_{-H/2}^{H/2} \left[1 - \left(\frac{2y}{H}\right)^2\right] dy \\ &= \frac{H^2}{16\eta} \left(-\frac{\Delta P}{L}\right) \int_{-1}^1 (1 - \xi^2) d\xi = \frac{H^2}{12\eta} \left(-\frac{\Delta P}{L}\right) \end{aligned}$$

Therefore,

$$v_x = \frac{3}{2} \langle v_x \rangle \left[1 - \left(\frac{2y}{H}\right)^2\right]$$

Symmetry boundary conditions:

$$\tau_{yx} = \frac{dv_x}{dy} = 0 \quad \text{at} \quad y = 0$$

Relaxed assumptions:

Kinematic assumption, $v_x = v_x(y)$, $v_y = v_y(y)$, $v_z = v_z(y)$.

Then, from the continuity $\frac{\partial v_y}{\partial y} = 0$ or $v_y = \text{constant}$.

Since $v_y = 0$ at $y = \pm H/2$, v_y must be zero everywhere.

The Navier-Stokes eq'ns then reduce to

$$\text{x component : } 0 = -\frac{\partial P}{\partial x} + \eta \frac{d^2 v_x}{dy^2}$$

$$\text{y component : } 0 = -\frac{\partial P}{\partial y} \quad : \quad P = P(x, z)$$

$$\text{z component : } 0 = -\frac{\partial P}{\partial z} + \eta \frac{d^2 v_z}{dy^2}$$

or x component : $\eta \frac{d^2 v_x}{dy^2} = \frac{\partial P}{\partial x}$

z component : $\eta \frac{d^2 v_z}{dy^2} = \frac{\partial P}{\partial z}$

Integrating the z component eq'n,

$$v_z = \frac{H^2}{8\eta} \left(-\frac{\partial P}{\partial z} \right) \left[1 - \left(\frac{2y}{H} \right)^2 \right]$$

and $\langle v_z \rangle = \frac{1}{H} \int_{-H/2}^{H/2} v_z dy = \frac{H^2}{12\eta} \left(-\frac{\partial P}{\partial z} \right)$

Since there is no net flow in the z direction, $\langle v_z \rangle = 0$,

and therefore, $\frac{\partial P}{\partial z} = 0$. Finally we have $v_z = 0$

Solution logic:

1. Assumptions on the nature of the velocity field.
(kinematic assumptions)
2. Solve the continuity and Navier–Stokes eq'ns.
3. Check the initial assumptions to have internal consistency.

Set of nonlinear PDE

- ⇒ absence of the proof of uniqueness of the solution
- ⇒ the possibility of another solution
- ⇒ requires the experimental check

8.3 Plane Couette Flow (Drag Flow)

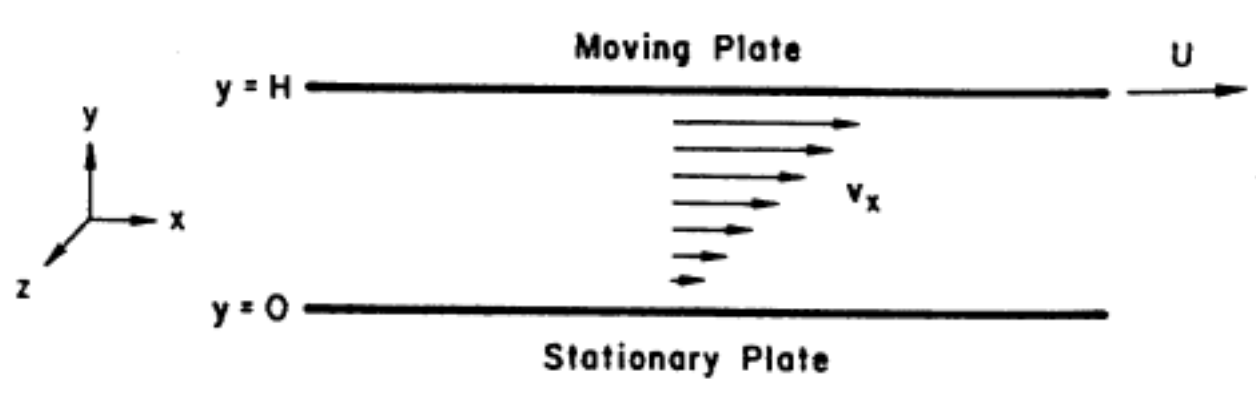


Fig. 8-3. Schematic of plane Couette flow.

Kinematic assumption:

$$v_x = v_x(y) , \quad v_y = v_z = 0 \quad \text{which satisfies the continuity eq'n.}$$

The Navier-Stokes eq'ns:

$$\text{x component} \quad 0 = -\frac{\partial P}{\partial x} + \eta \frac{d^2 v_x}{dy^2}$$

$$\text{y component} \quad 0 = -\frac{\partial P}{\partial y} , \quad \text{z component} \quad 0 = -\frac{\partial P}{\partial z}$$

$$\Rightarrow P = P(x)$$

Engineering Bernoulli eq'n:

no work, no losses, $\langle v_x \rangle$ is independent of x ,

$\therefore P$ is also independent of $x \Rightarrow$ we assume that $\frac{\partial P}{\partial x} = 0$

Then, we have $\frac{d^2 v_x}{dy^2} = 0 \Rightarrow v_x = C_1 y + C_2$

Boundary conditions:

$$v_x = 0 \text{ at } y = 0 \Rightarrow C_2 = 0$$

$$v_x = U \text{ at } y = H \Rightarrow C_1 = U/H$$

Therefore, $v_x = \frac{Uy}{H}$ and the shear stress is

$$\tau_{yx} = \eta \left(\frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right) = \eta \frac{dv_x}{dy} = \eta \frac{U}{H} \quad : \text{ independent of position}$$

8.4 Poiseuille Flow

Consider steady fully developed flow of an incompressible Newtonian fluid in a long, smooth, round tube of radius R .

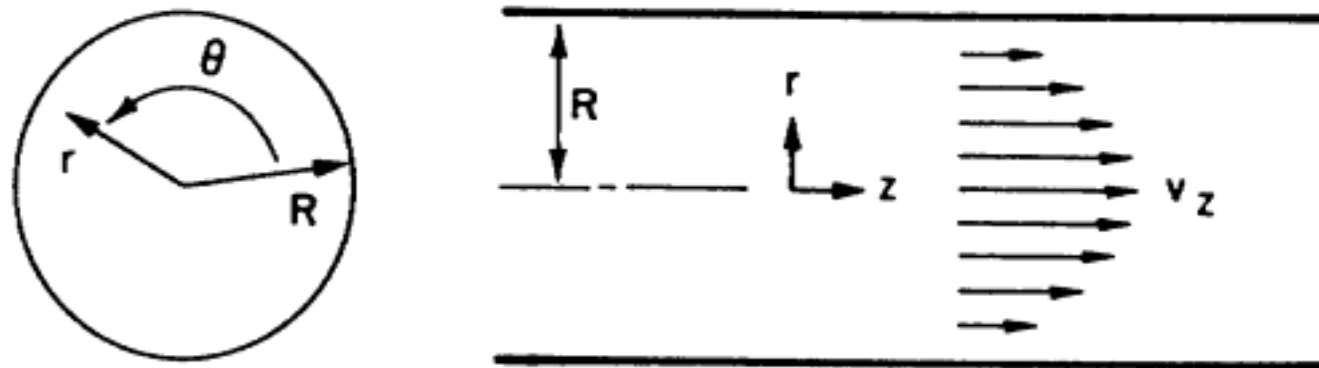


Fig. 8-4. Schematic of laminar flow in a long smooth, round tube.

Kinematic assumptions (using the cylindrical coordinates):

$$v_z = v_z(r) , \quad v_r = v_\theta = 0$$

The continuity eq'n:

$$\frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z} = 0 \quad \text{: satisfied}$$

Navier-Stokes eq'ns:

$$r \text{ component:} \quad 0 = -\frac{\partial P}{\partial r}$$

$$\theta \text{ component:} \quad 0 = -\frac{1}{r} \frac{\partial P}{\partial \theta}$$

$$z \text{ component:} \quad 0 = -\frac{\partial P}{\partial z} + \eta \frac{1}{r} \frac{d}{dr} \left(r \frac{dv_z}{dr} \right)$$

$$r \text{ and } \theta \text{ component eq'ns} \quad \Rightarrow \quad P = P(z)$$

$$\text{and } z \text{ component eq'n} \quad \Rightarrow \quad \frac{1}{r} \frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \frac{1}{\eta} \frac{dP}{dz}$$

f'n of r only f'n of z only

Therefore, $\frac{1}{r} \frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \frac{1}{\eta} \frac{dP}{dz} = \text{constant} = \frac{1}{\eta} \frac{\Delta P}{L}$

: pressure gradient is linear in pipe length

We rewrite the z component eq'n as

$$\frac{d}{dr} \left(r \frac{dv_z}{dr} \right) = \frac{1}{\eta} \frac{\Delta P}{L} r$$

After first integration,

$$r \frac{dv_z}{dr} = \frac{1}{2\eta} \frac{\Delta P}{L} r^2 + C_1$$

or $\frac{dv_z}{dr} = \frac{1}{2\eta} \frac{\Delta P}{L} r + \frac{C_1}{r}$

After second integration,

$$v_z = \frac{1}{4\eta} \frac{\Delta P}{L} r^2 + C_1 \ln r + C_2$$

Since v_z is finite at $r = 0 \Rightarrow C_1 = 0$

No-slip boundary condition:

$$v_z = 0 \text{ at } r = R \Rightarrow 0 = \frac{1}{4\eta} \frac{\Delta P}{L} R^2 + C_2$$

Therefore, the velocity profile becomes

$$v_z(r) = \frac{R^2}{4\eta} \left(-\frac{\Delta P}{L}\right) \left[1 - \left(\frac{r}{R}\right)^2\right] = 2 \langle v_z \rangle \left[1 - \left(\frac{r}{R}\right)^2\right]$$

The average velocity is

$$\langle v_z \rangle = \frac{1}{\pi R^2} \int_{area} v_z dA = \frac{R^2}{8\eta} \left(-\frac{\Delta P}{L}\right)$$

: equivalent to the Hagen-Poiseuille eq'n

The friction factor:

$$f = \frac{(-\Delta P)R}{\rho \langle v_z \rangle^2 L} = \frac{8\eta}{\rho \langle v_z \rangle R} = \frac{16\eta}{\rho \langle v_z \rangle D} = \frac{16}{\text{Re}}$$

Range of solution:

The pipe must be long relative to an entry length
of approximately $0.055DRe$.

$Re < 2100$, becomes unstable solution for $Re > 2100$.
(turbulence)

Stability of steady-state solution:

$$\frac{dv}{dt} = (v-1)(v-2) \quad , \quad v(0) = A$$

steady-state solution: $v = 1$ and $v = 2$

transient solution:
$$v(t) = \frac{2(A-1) - (A-2)e^t}{A-1 - (A-2)e^t}$$

For $A < 2$, $v(t) \rightarrow 1$ as $t \rightarrow \infty$.

For $A > 2$, $v(t) \rightarrow \infty$ as $t \rightarrow \ln\left(\frac{A-1}{A-2}\right)$.

(no steady-state)

8.5 Wire Coating

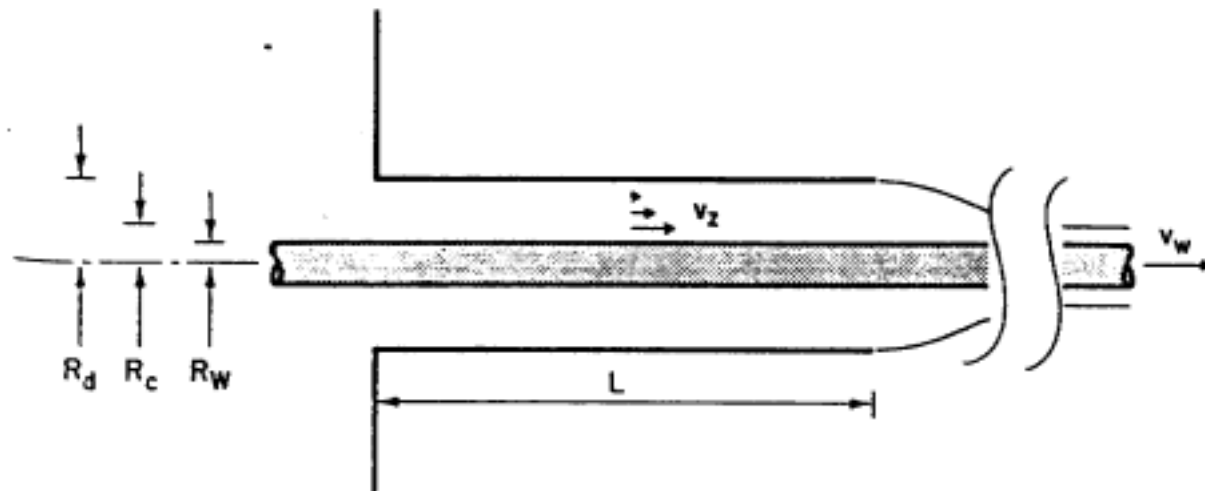


Fig. 8-5. Schematic of wire coating.

$$R_c = R_c(R_w, R_d)$$

R_c : the ultimate radius of the coated wire

R_w : the radius of the uncoated wire

R_d : the die radius

The mass balance on the coating material:

$$Q = V_w(\pi R_c^2 - \pi R_w^2) = \int_{R_w}^{R_d} 2\pi r v_z(r) dr$$

downstream within the die

$$\Rightarrow R_c = \left[R_w^2 + \frac{2}{V_w} \int_{R_w}^{R_d} r v_z(r) dr \right]^{1/2}$$

To obtain $v_z(r)$,

Kinematics: $v_z = v_z(r), \quad v_r = v_\theta = 0$

\Rightarrow continuity is satisfied

Navier-Stokes eq'n:

z component $0 = \eta \left[\frac{1}{r} \frac{d}{dr} \left(r \frac{dv_z}{dr} \right) \right]$

After the first integration, $r \frac{dv_z}{dr} = \text{constant} = C_1$

The second integration : $v_z(r) = C_1 \ln r + C_2$

Apply the boundary conditions to determine C_1 and C_2

$$r = R_w : V_w = C_1 \ln R_w + C_2$$

$$r = R_d : 0 = C_1 \ln R_d + C_2$$

$$\Rightarrow C_1 = \frac{V_w}{\ln R_w / R_d} , \quad C_2 = -\frac{V_w \ln R_d}{\ln R_w / R_d}$$

$$\therefore v_z(r) = V_w \frac{\ln r / R_d}{\ln R_w / R_d} : \text{ independent of viscosity } \eta$$

Finally we obtain

$$R_c = \left(\frac{R_d^2 - R_w^2}{2 \ln R_d / R_w} \right)^{1/2} : \text{ independent of } \eta \text{ and } V_w$$

The force required to pull the wire through the die:

$$F_w = 2\pi R_w L \tau_{rz} \Big|_{r=R_w}$$

where $\tau_{rz} \Big|_{r=R_w} = \eta \left(\frac{\partial v_z}{\partial r} + \frac{\partial v_r}{\partial z} \right) \Big|_{r=R_w} = \frac{\eta V_w}{R_w \ln R_w / R_d}$

$$\therefore F_w = \frac{2\pi\eta V_w L}{\ln R_w / R_d} < 0$$

8.6 Torsional Flow

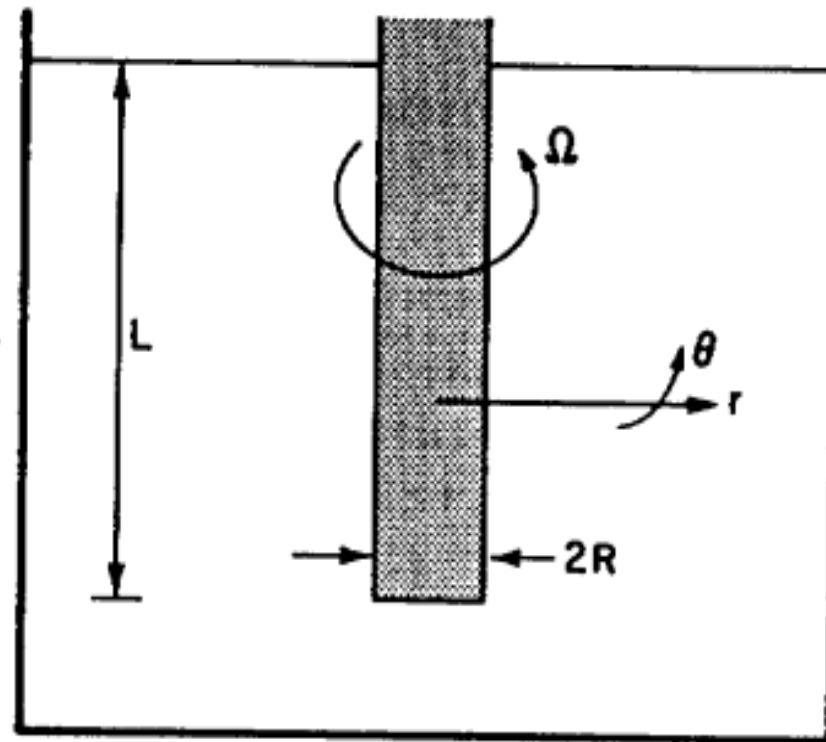


Fig. 8-6. Schematic of torsional flow.

$L \gg R$, neglect end effects

Kinematic assumption :

$$v_\theta = v_\theta(r), \quad v_r = v_z = 0 \quad \Rightarrow \quad \text{satisfies the continuity}$$

Navier-Stokes eq'n :

$$r \text{ component} \quad -\rho \frac{v_\theta^2}{r} = -\frac{\partial P}{\partial r}$$

$$\theta \text{ component} \quad 0 = \mu \frac{d}{dr} \left[\frac{1}{r} \frac{d}{dr} (rv_\theta) \right]$$

$$z \text{ component} \quad 0 = -\frac{\partial P}{\partial z} \quad : \quad P \text{ is independent of } z$$

The integration of θ component eq'n gives

$$\frac{1}{r} \frac{d}{dr} (rv_\theta) = \text{constant} = C_1 \quad \text{or} \quad \frac{d}{dr} (rv_\theta) = C_1 r$$

$$\Rightarrow \quad v_\theta = \frac{1}{2} C_1 r + \frac{C_2}{r}$$

: increases without bound as r increases

$$\therefore C_1 = 0$$

Apply no-slip boundary condition to determine C_2

$$r = R: \quad v_\theta = R\Omega = \frac{C_2}{R} \quad \Rightarrow \quad v_\theta = \frac{R^2\Omega}{r}$$

The shear stress on the cylinder wall :

$$\tau_{r\theta} \big|_{r=R} = \eta \left[r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right] \big|_{r=R} = -2\eta\Omega$$

The total torque on the cylinder :

$$G = \int_0^{2\pi} LR^2 \tau_{r\theta} \big|_{r=R} d\theta = -4\pi R^2 L \eta \Omega$$

Pressure and cavitation :

$$r \text{ component eq'n} \Rightarrow \frac{dP}{dr} = \frac{\rho v_{\theta}^2}{r} = \frac{\rho (R^2 \Omega)^2}{r^3}$$

$$\text{After the integration,} \quad P = P_0 - \frac{\rho (R^2 \Omega)^2}{2r^2}$$

* P_0 : maximum pressure at $r \rightarrow \infty$

* minimum pressure at the cylinder surface

$$= P_0 - \frac{1}{2} \rho (R\Omega)^2$$

The cavitation will occur if $P_0 - \frac{1}{2} \rho (R\Omega)^2 < P_{vp}$

$$\text{or } R\Omega \geq \sqrt{\frac{2(P_0 - P_{vp})}{\rho}}$$

8.8 Tube Flow of a Power-law Fluid

Power-law fluid :

In plane Couette flow : $\eta(\Gamma_s) = K|\Gamma_s|^{n-1}$

General form in three-dimensional flow : $\eta = K\left|\frac{1}{2}\Pi\right|^{(n-1)/2}$

Kinematic assumption :

$v_z = v_z(r), \quad v_r = v_\theta = 0 \quad \Rightarrow$ satisfies the continuity

nonzero stress components : $\tau_{rz}(r)$

The momentum eq'ns :

$$r \text{ component: } 0 = -\frac{\partial P}{\partial r}$$

$$\theta \text{ component: } 0 = -\frac{1}{r} \frac{\partial P}{\partial \theta}$$

$$z \text{ component: } 0 = -\frac{\partial P}{\partial z} + \frac{1}{r} \frac{d}{dr}(r\tau_{rz})$$

r and θ components $\Rightarrow P = P(z)$

Then, z component: $\frac{1}{r} \frac{d}{dr} (r\tau_{rz}) = \frac{dP}{dz} = \frac{\Delta P}{L}$

After the integration, we obtain $\tau_{rz} = \frac{\Delta P}{2L} r + \frac{C_1}{r}$

Since the stress must remain finite at the centerline, $C_1 = 0$

$\therefore \tau_{rz} = \frac{\Delta P}{2L} r$: a general result for fully developed pipe flow

In the pipe flow, $\frac{1}{2} \Pi = \left(\frac{dv_z}{dr} \right)^2 \Rightarrow \tau_{rz} = K \left| \frac{dv_z}{dr} \right|^{n-1} \frac{dv_z}{dr}$

Therefore, $K \left| \frac{dv_z}{dr} \right|^{n-1} \frac{dv_z}{dr} = \frac{\Delta P}{2L} r$

Since ΔP and $\frac{dv_z}{dr}$ are negative,

$$\frac{dv_z}{dr} = - \left(-\frac{\Delta P}{2KL} \right)^{1/n} r^{1/n}$$

After the integration,

$$v_z(r) = \frac{n}{n+1} \left[\frac{R^{n+1}}{2K} \left(-\frac{\Delta P}{L} \right) \right]^{1/n} \left[1 - \left(\frac{r}{R} \right)^{(n+1)/n} \right]$$

and $\langle v_z \rangle = \frac{n}{(3n+1)} \left[\frac{R^{n+1}}{2K} \left(-\frac{\Delta P}{L} \right) \right]^{1/n}$

v_z can be rewritten, using $\langle v_z \rangle$, as

$$v_z(r) = \frac{3n+1}{n+1} \langle v_z \rangle \left[1 - \left(\frac{r}{R} \right)^{(n+1)/n} \right]$$

The profile is blunter than that for a Newtonian fluid.

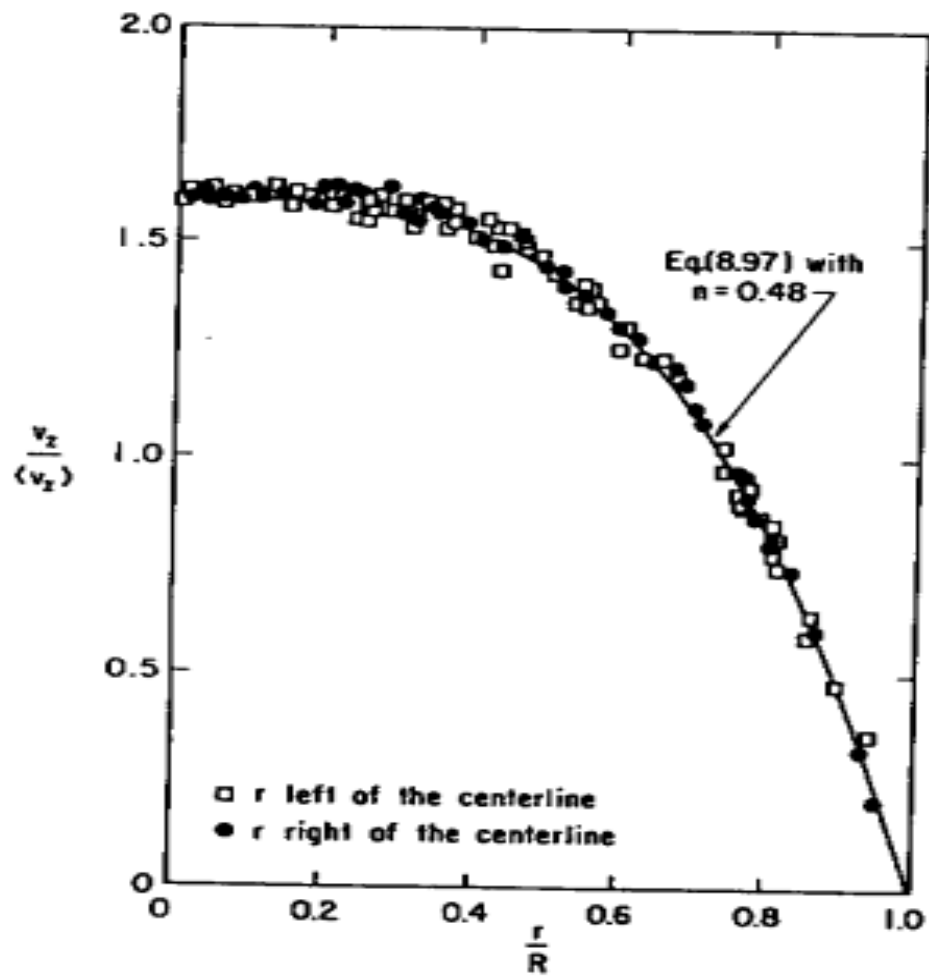


Fig. 8-8. Velocity profile in a tube for a solution of polyacrylamide in water.